

A Community Earth System Emulator for UQ and Calibration

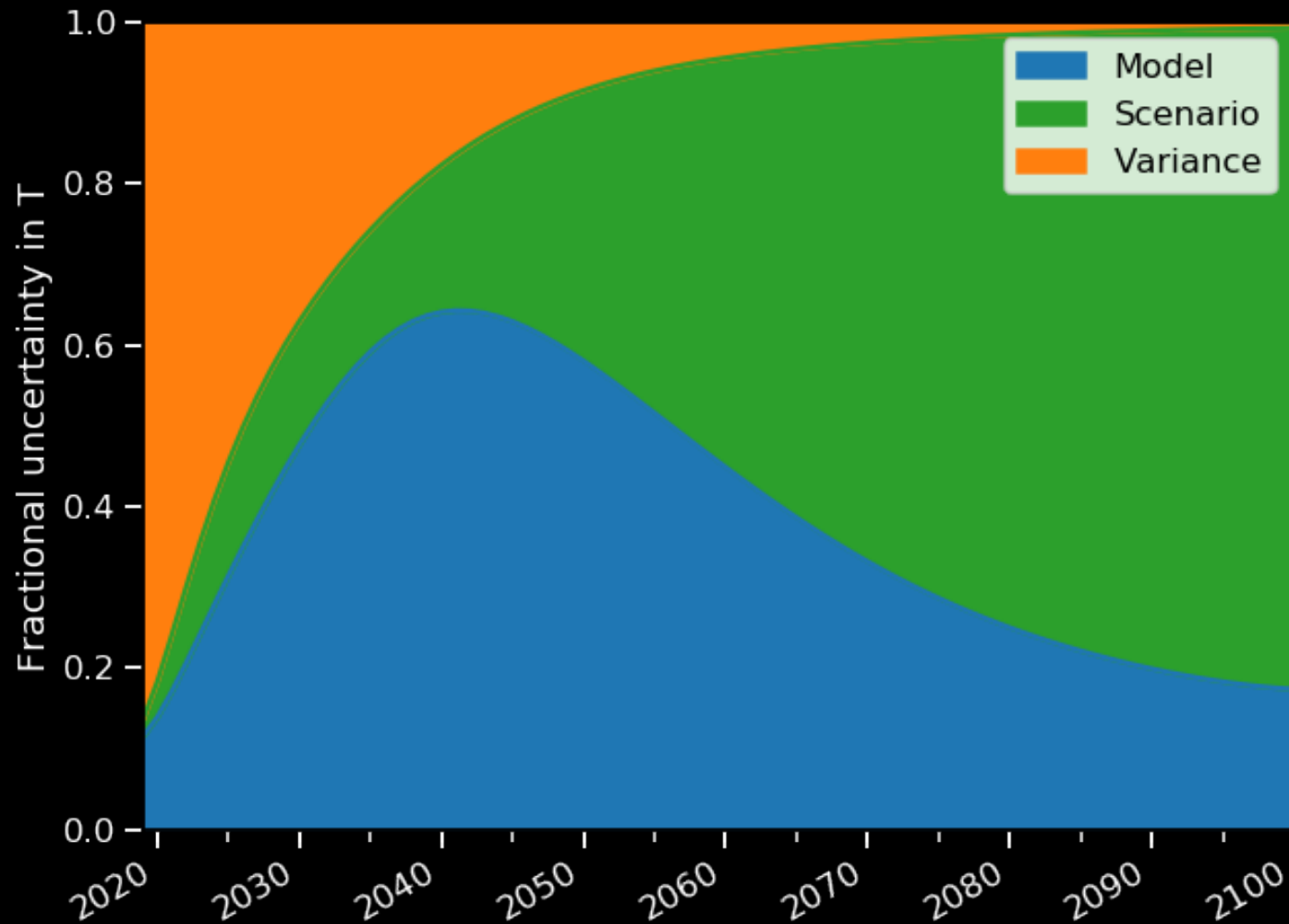
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CESM Parameter Estimation Cross Working Group

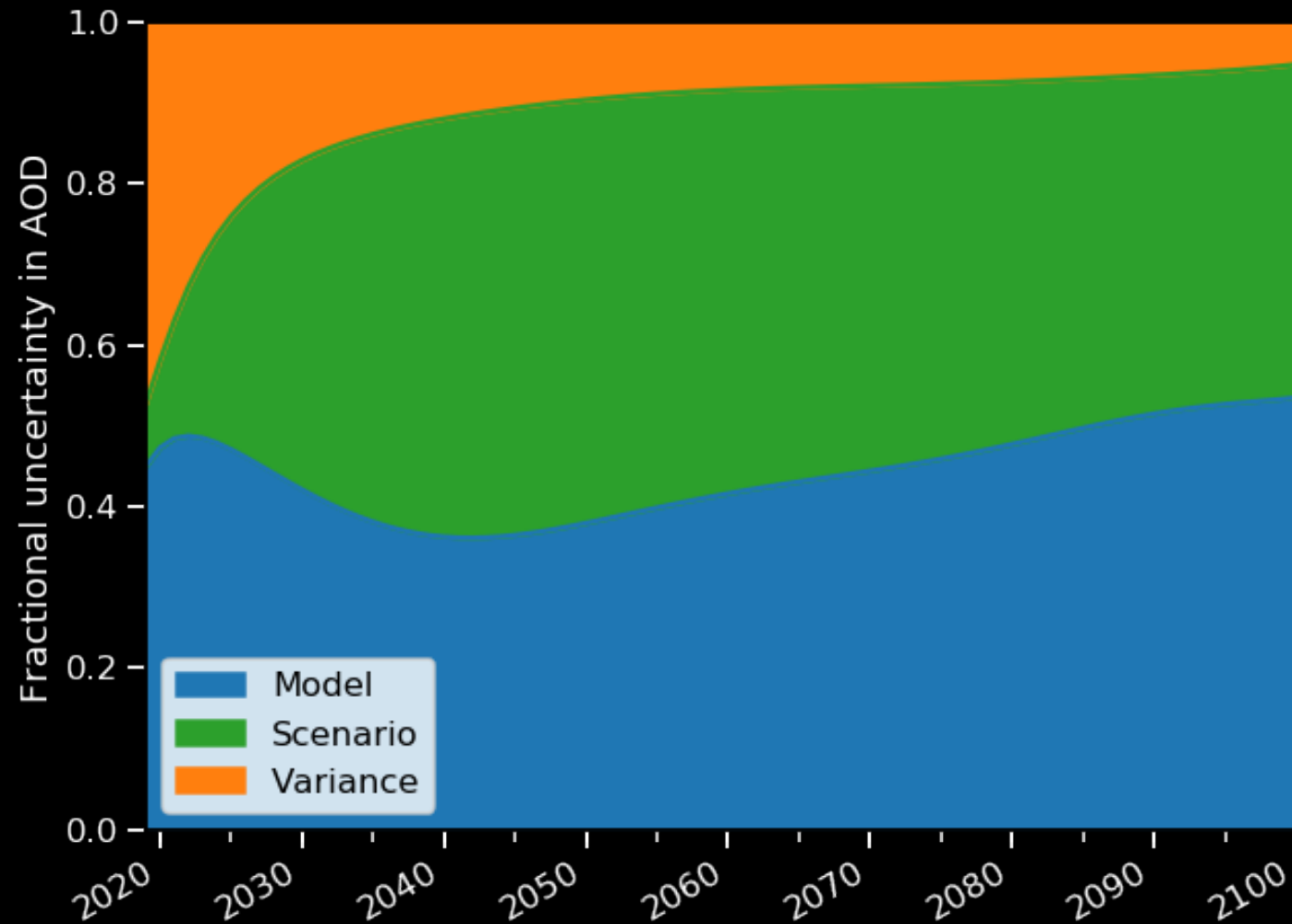
12th June 2023



Sources of uncertainty



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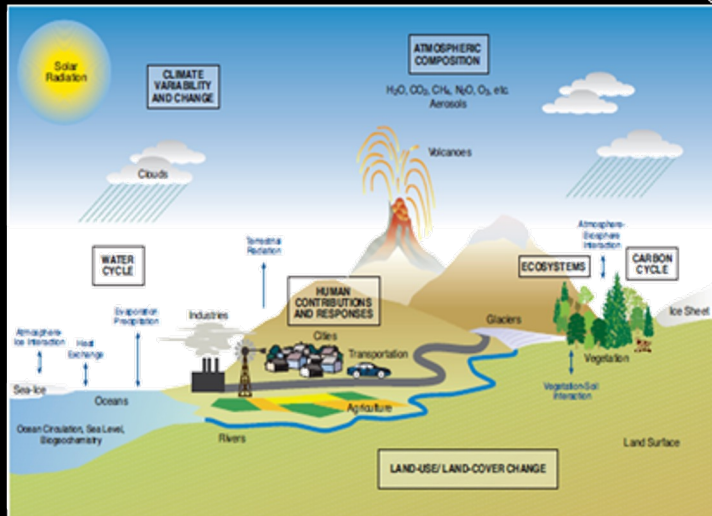
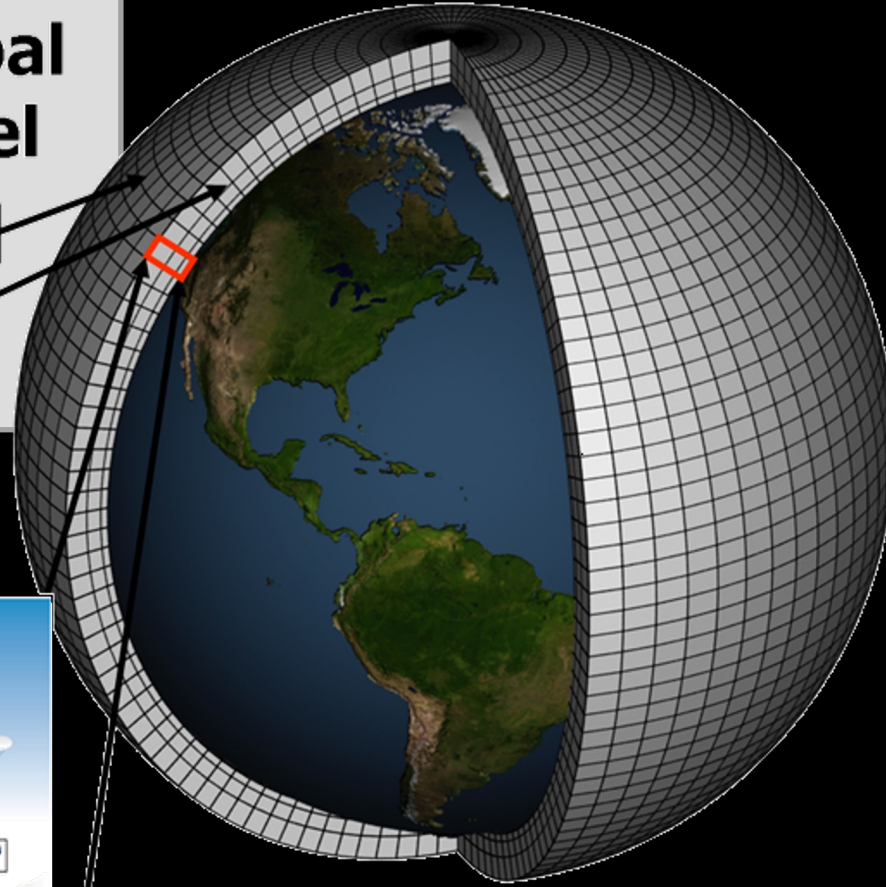


Climate models

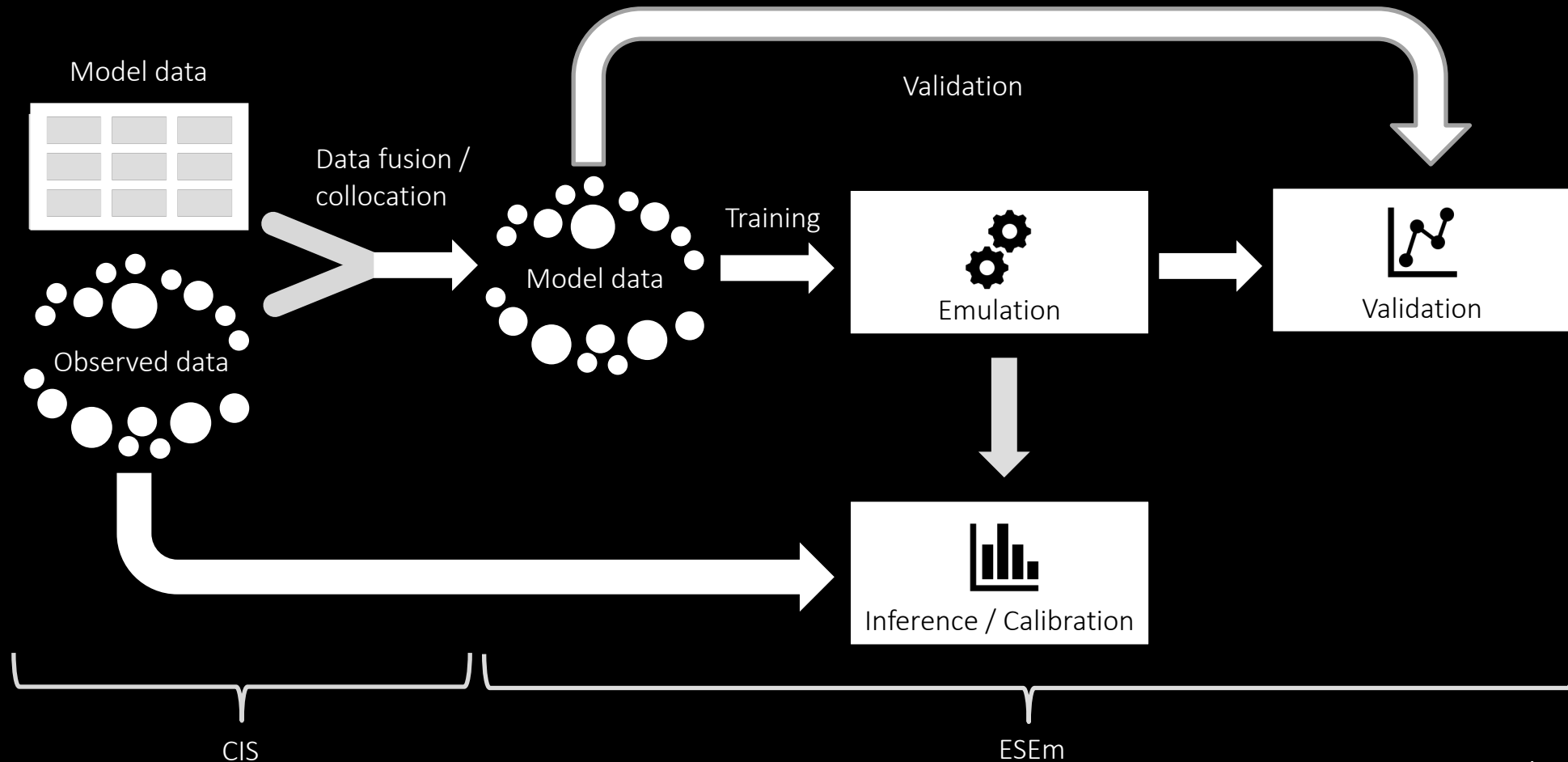
Schematic for Global Atmospheric Model

Horizontal Grid (Latitude-Longitude)

Vertical Grid (Height or Pressure)



Earth System Emulator (ESEm)



Exploring parametric uncertainty

- A climate model is a function \mathcal{F} of input forcings X and parameters θ and generates outputs Y : $\mathcal{F}(X, \theta) = Y$.
- Given a set of observations of Y , denoted Y^0 , we would like to calculate the inverse: $\mathcal{F}^{-1}(Y^0) = \theta$.
- Or, more precisely, we would like to know the posterior probability distribution of the input parameters:

$$p(\theta|Y^0) = \frac{p(Y^0|\theta)p(\theta)}{p(Y^0)}$$

Likelihood-free inference

- We cannot compute the full likelihood but can approximate it using Approximate Bayesian computation (ABC; or rejection sampling):
 1. Draw θ from $p(\theta)$
 2. Calculate $\mathcal{F}(\theta)$ to determine Y
 3. Accept θ if $\rho(Y^0, Y) \leq \epsilon$
- As $\epsilon \rightarrow \infty$, we get observations from the prior, $p(\theta)$
- As $\epsilon \rightarrow 0$, we generate observations from $p(\theta|Y^0)$
- In practice we need many, many samples and so a surrogate model, or emulator, is used: $\mathcal{E}(\theta) \sim \mathcal{F}(\theta)$

Implausibility

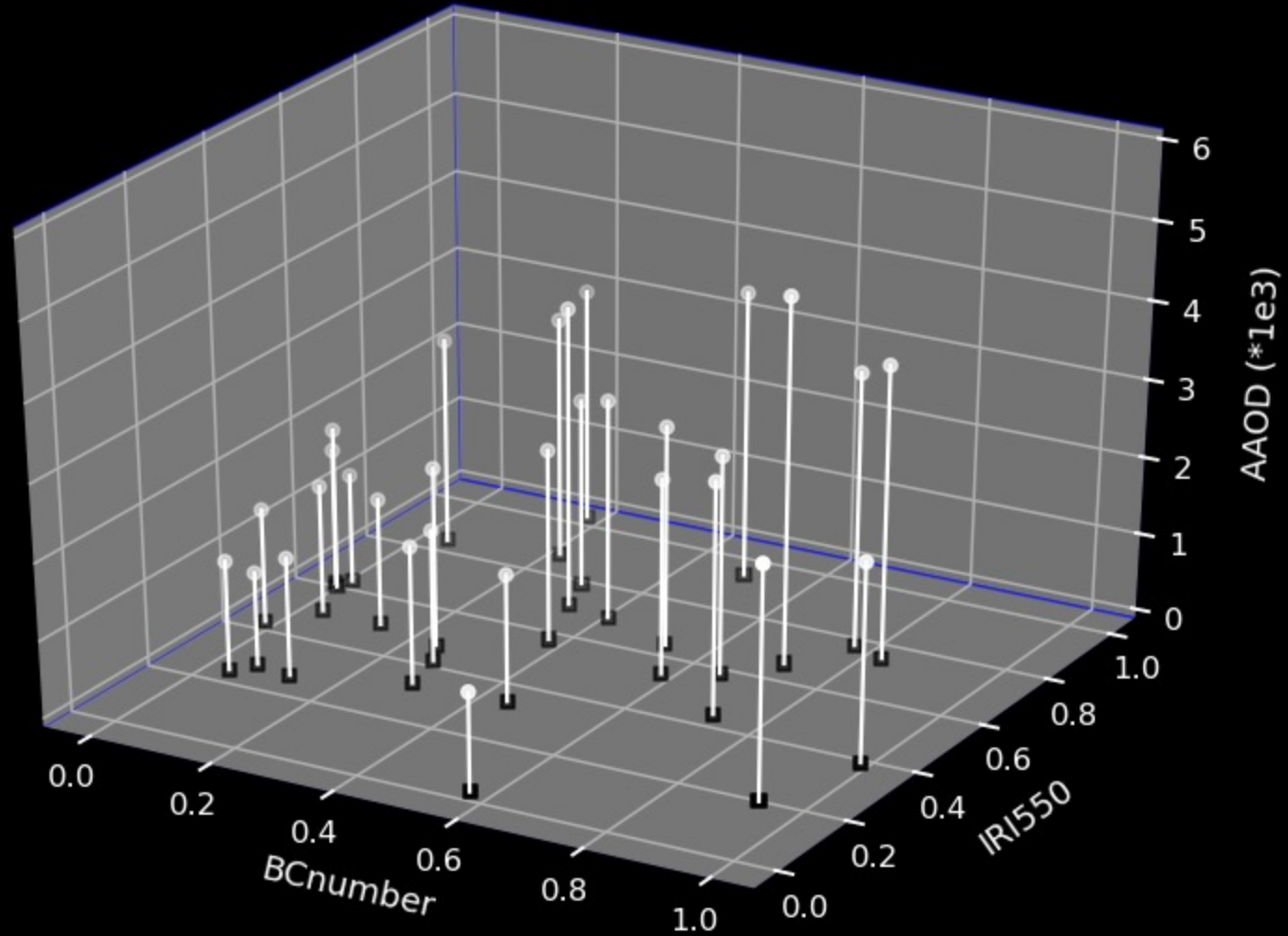
- In practice, we need to define the distance, $\rho(Y^0, Y)$
- We use the concept of an implausibility metric:

$$I(\theta) = \frac{|Y^0 - E[\eta(\theta)]|}{\sqrt{[Var(\phi(\theta)) + Var(\epsilon) + Var(\delta)]}}$$

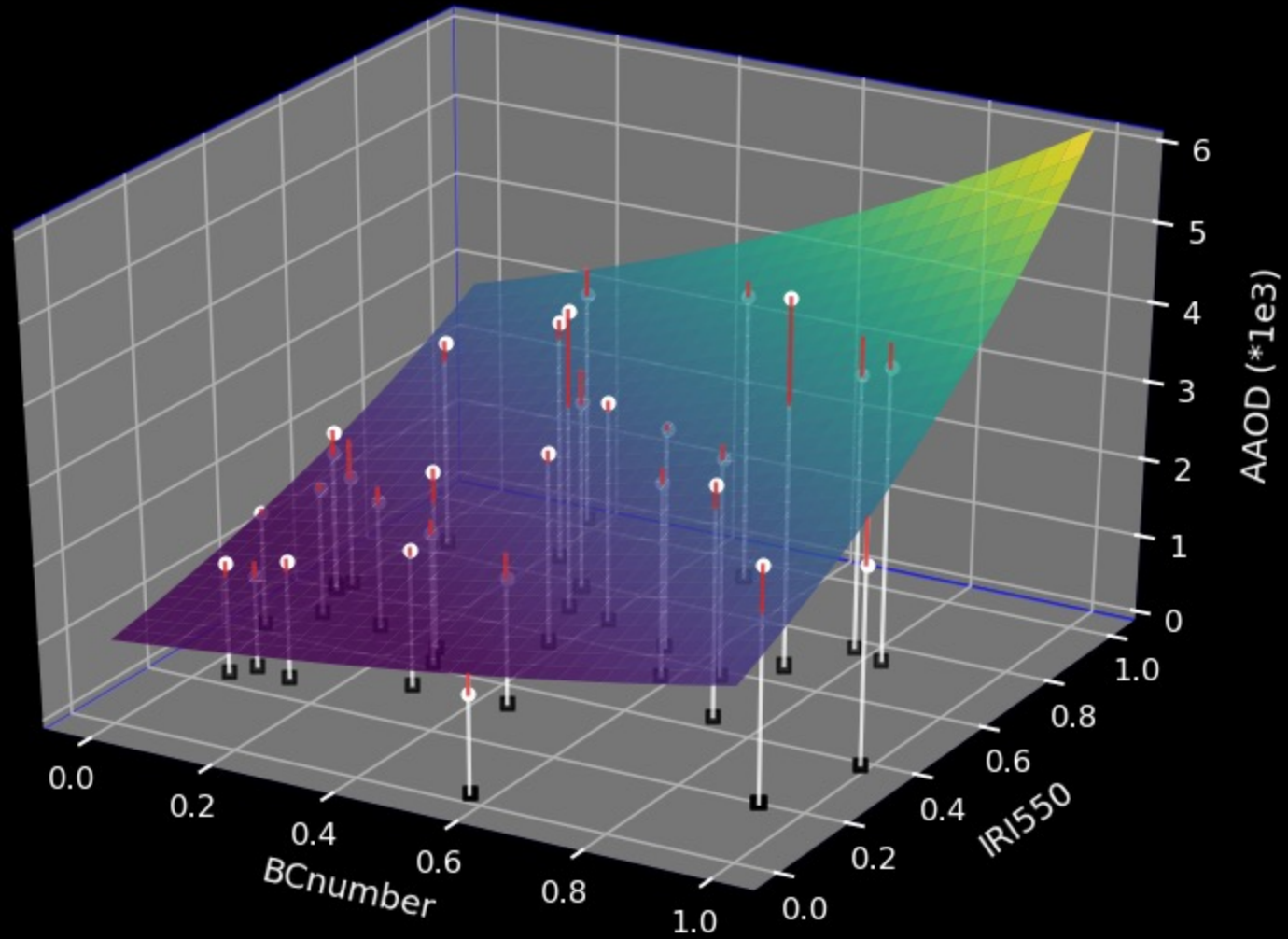
Observation
Model output
[Prediction from emulator]
Emulator prediction uncertainty
Observational uncertainty
Structural uncertainty

- Assuming this distribution is unimodal, we can then use the 3σ to rule out parameter combinations at 95% confidence

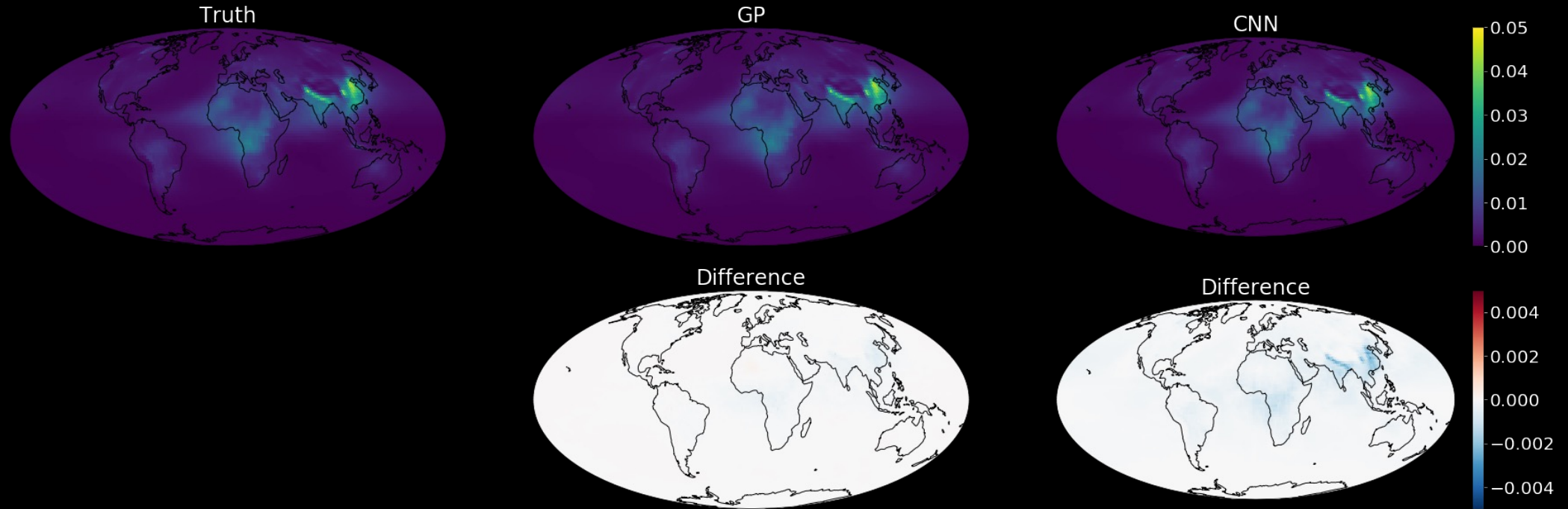
Emulation



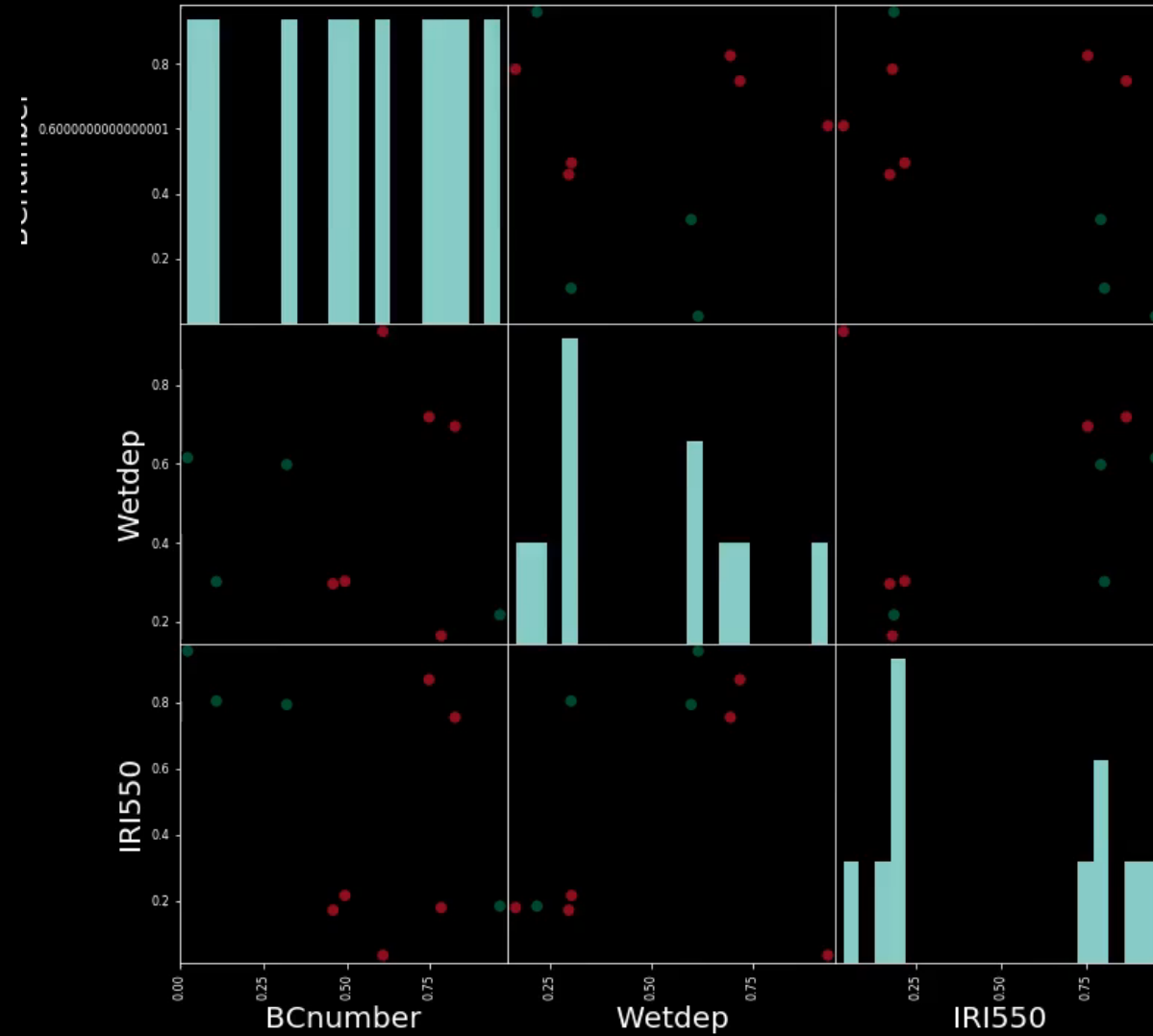
Emulation



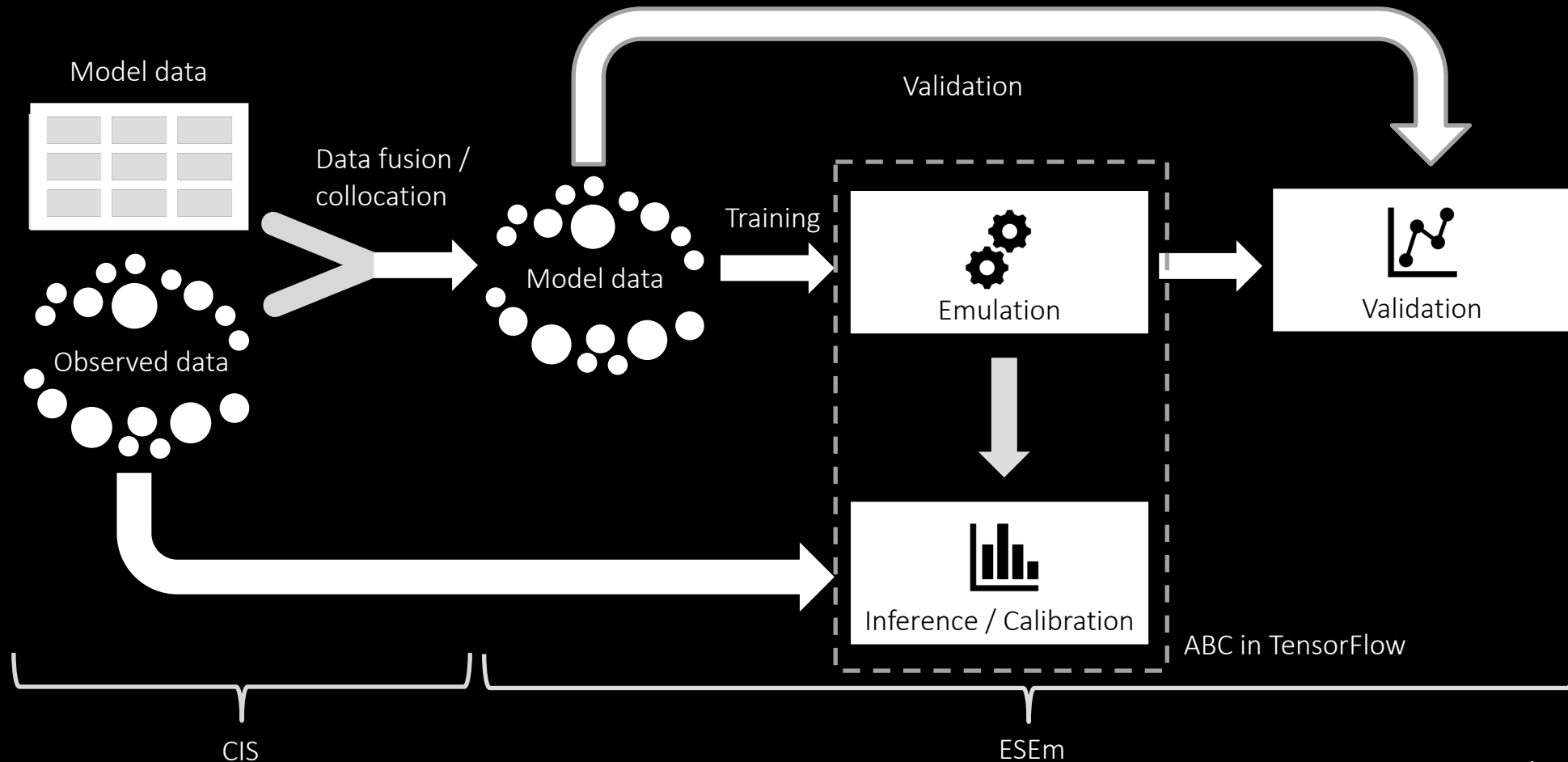
Emulation



Sampling



Earth System Emulator (ESEm)

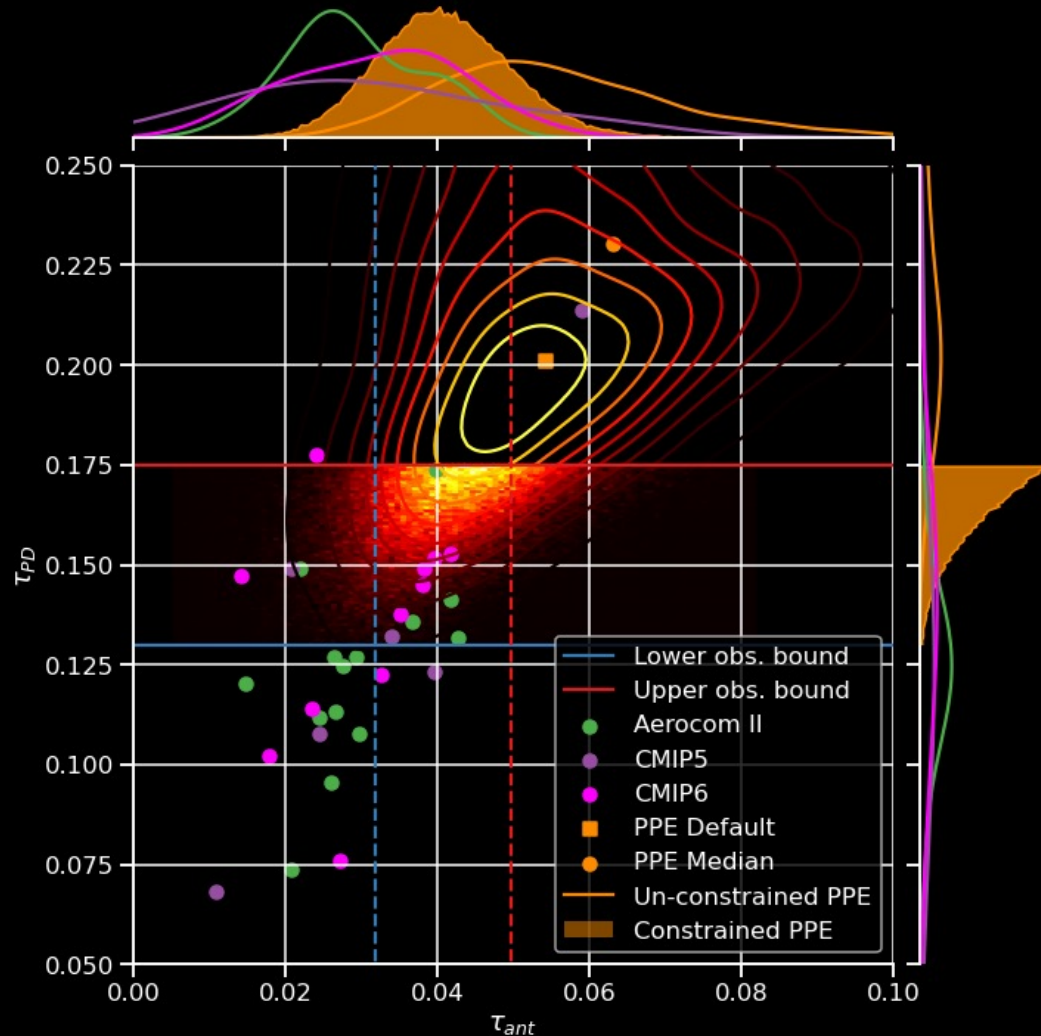


Parametric uncertainty

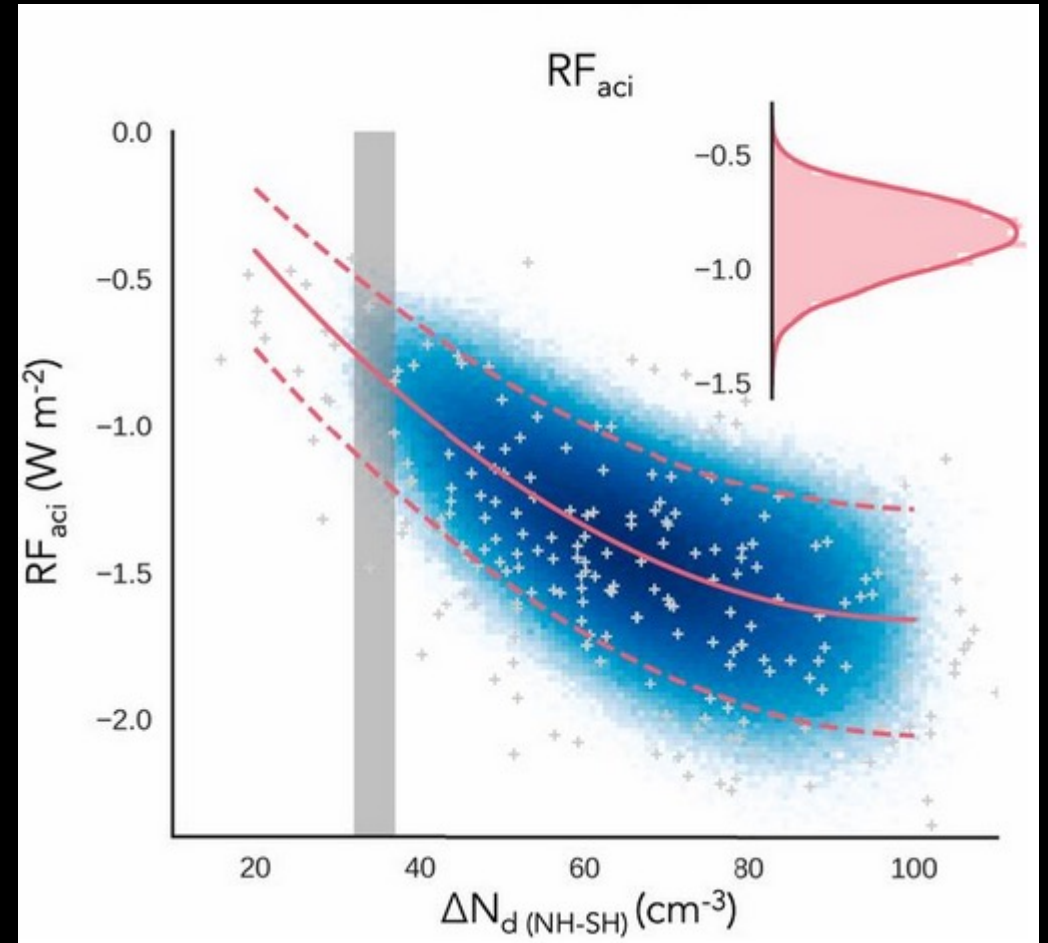
Table 1. The uncertain parameters and emissions factors

Parameter Key	Parameter name	Description of parameter	Uncertainty range	Effect
P1	BL_NUC	Boundary layer nucleation rate coeff (A)	$3.2e^{-7}$ – $2e^{-4} s^{-1}$	Absolute
P2	FT_NUC	Free troposphere nucleation rate	0.01–10	Scaled
P3	AGEING	Ageing “rate” from insoluble to soluble	0.3–5 monolayer	Absolute
P4	ACT_DIAM	Cloud drop activation dry diameter	50–100 nm	Absolute
P5	SO2O3_CLEAN	pH of cloud drops (controls SO ₂ + O ₃)	pH 4–6.5	Absolute
P6	SO2O3_POLL	pH of cloud drops (SO ₂ + O ₃)	pH 3.5–5	Absolute
P7	NUC_SCAV_DIAM	Nucleation scavenging diameter offset dry diameter	0–50 nm	Absolute
P8	NUC_SCAV_ICE	Nucleation scavenging fraction (accumulation mode) in mixed and ice clouds ($T < -15$ °C)	0–1	Scaled
P9	DRYDEP_AER_AIT	Dry deposition velocity of Aitken mode aerosol	0.5–2	Scaled
P10	DRYDEP_AER_ACC	Dry deposition velocity of accumulation mode aerosol	0.1–10	Scaled
P11	ACC_WIDTH	Modal width (accumulation soluble/insoluble)	1.2–1.8	Absolute
P12	AIT_WIDTH	Modal width (Aitken soluble/insoluble)	1.2–1.8	Absolute
P13	NUCAIT_WIDTH	Mode separation diameter (nucleation/Aitken)	9–18 nm	Absolute
P14	AITACC_WIDTH	Mode separation diameter (Aitken/accumulation)	$0.9-2 \times \text{ACT_DIAM}$	Scaled
P15	FF_EMS	BC/OC mass emission rate (fossil fuel)	0.5–2	Scaled
P16	BB_EMS	BC/OC mass emission rate (biomass burning)	0.25–4	Scaled
P17	BF_EMS	BC/OC mass emission rate (biofuel)	0.25–4	Scaled
P18	FF_DIAM	BC/OC emitted mode diameter (fossil fuel)	30–80 nm	Absolute
P19	BB_DIAM	BC/OC emitted mode diameter (biomass burning)	50–200 nm	Absolute
P20	BF_DIAM	BC/OC emitted mode diameter (biofuel)	50–200 nm	Absolute
P21	PRIM.SO4.FRAC	Mass fraction of SO ₂ converted to new SO ₄ ²⁻ particles in sub-grid power plant plumes	0–1 %	Absolute
P22	PRIM.SO4.DIAM	Mode diameter of new sub-grid SO ₄ ²⁻ particles	20–100 nm	Absolute
P23	SS_ACC	Sea spray mass flux (coarse/accumulation)	0.2–5	Scaled
P24	ANTH_SO2	SO ₂ emission flux (anthropogenic)	0.6–1.5	Scaled
P25	VOLC_SO2	SO ₂ emission flux (volcanic)	0.5–2	Scaled
P26	DMS_FLUX	DMS emission flux	0.5–2	Scaled
P27	BIO_SOA	Biogenic monoterpene production of SOA	$5-360 \text{ Tg a}^{-1}$	Absolute
P28	ANTH_SOA	Anthropogenic VOC production of SOA	$2-112 \text{ Tg a}^{-1}$	Absolute

Constraining parametric uncertainty



Watson-Parris et al. *GRL* 2020



McCoy et al. 2020

Calibrating CESM2 PPE on Casper: Setup

```
[ ]: import xarray as xr
import numpy as np
import pandas as pd

from esem import gp_model
from esem.utils import validation_plot, get_param_mask

[ ]: def global_mean(ds):
    weights = np.cos(np.deg2rad(ds.lat))
    return ds.weighted(weights).mean(['lat', 'lon'])

def get_ensemble_member(ds):
    fname = ds.encoding['source']
    member = int(fname.split('.')[-4])
    return ds.assign_coords(member=member).expand_dims('member')
```


Calibrating CESM2 PPE on Casper: Data Reading

```
[ ]: data_path = '/glade/campaign/cgd/projects/ppe/cam_ppe/rerun_PPE_250/'
      params=xr.open_dataset(data_path+"parameter_262_w_control.nc").to_pandas().drop(columns=['Sample_nmb'])
      ds = xr.open_mfdataset(data_path+'PD/PD_timeseries/*/atm/hist/cc_PPE_250_ensemble_PD.*.h0.SWCF.nc', preprocess=get_ensemble_member)
      SWCF = global_mean(ds['SWCF']).mean('time').compute()

[ ]: # Some of the PPE members are missing data so just select the params we actually have
      sub_params = params.iloc[SWCF.member.values]
      # Unit normalise all the parameters
      ppe_params = (sub_params - sub_params.min()) / (sub_params.max() - sub_params.min())

[ ]: # We can use an information criterion to choose the best parameters automatically:
      best_params = ppe_params[ppe_params.columns[get_param_mask(ppe_params, SWCF)]]
      best_params.columns

[ ]: n_test = 25

      X_test, X_train = best_params[:n_test], best_params[n_test:]
      Y_test, Y_train = SWCF[:n_test], SWCF[n_test:]
```

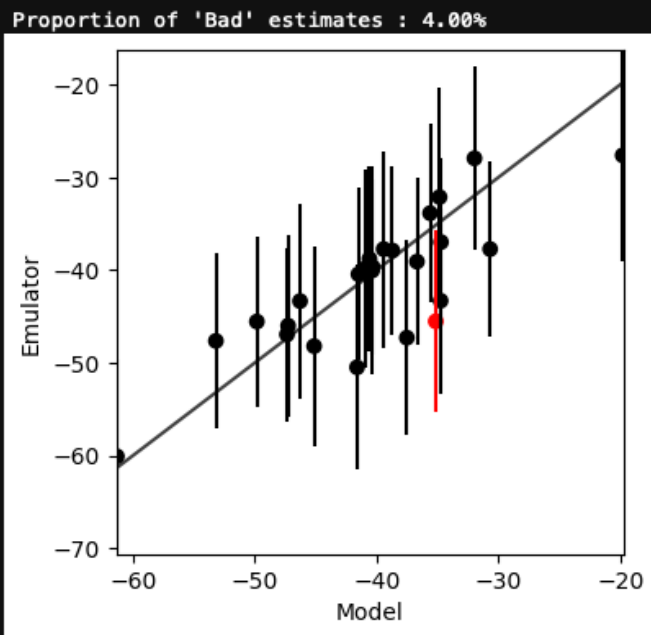
Calibrating CESM2 PPE on Casper: Emulation

```
[ ]: # Can try different kernels here
gp = gp_model(X_train, Y_train, kernel=['Linear', 'RBF'])

[ ]: gp.train()

[ ]: m, v = gp.predict(X_test)

[21]: validation_plot(Y_test.data, m, v, figsize=(4,4))
```



Calibrating CESM2 PPE on Casper: Calibration

```
[ ]: from esem.utils import get_random_params
     from esem.abc_sampler import ABCSampler, constrain

[ ]: # Setup sampler with 1 million points
     sample_points = pd.DataFrame(data=get_random_params(23, int(1e6)), columns=X_train.columns)
     sampler = ABCSampler(gp, np.asarray([-40.5]), obs_uncertainty=0.5)

[ ]: valid_samples = sampler.batch_constrain(sample_points, batch_size=10000)

[28]: print("Remaining points: {}".format(valid_samples.sum()))
```

Remaining points: 100

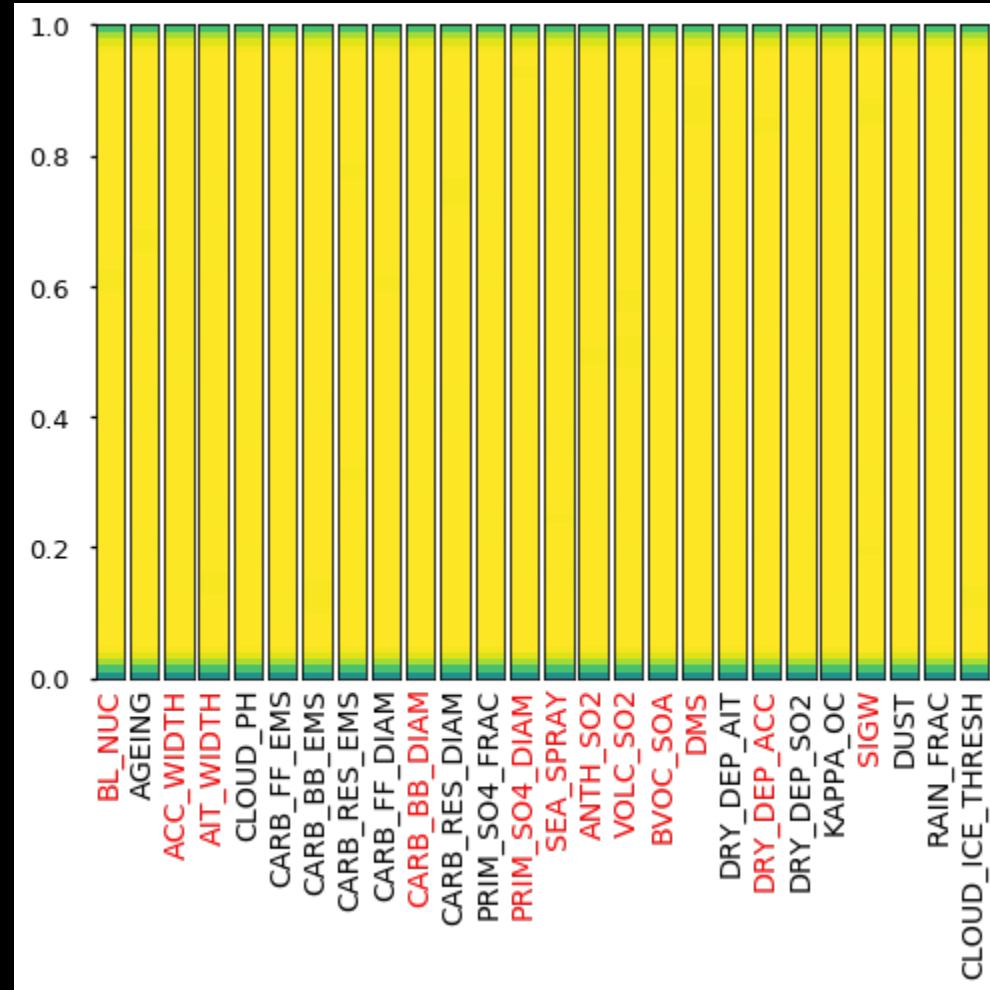
Conclusions and outlook

- Climate model emulation is an important tool for constraining parameter uncertainty, and has been used for a while
- A fast, open tool leveraging modern ML libraries is introduced which makes the whole workflow straightforward and reproducible
- We also demonstrate how such tools can be used for exploring uncertainty in future emissions scenarios
- ESEm is designed to be easily extended to include other ML models
- We welcome feedback and suggestions, especially with pull requests!

<https://github.com/duncanwp/ESEm>

Spare slides

Getting your priors straight



Getting your priors straight

